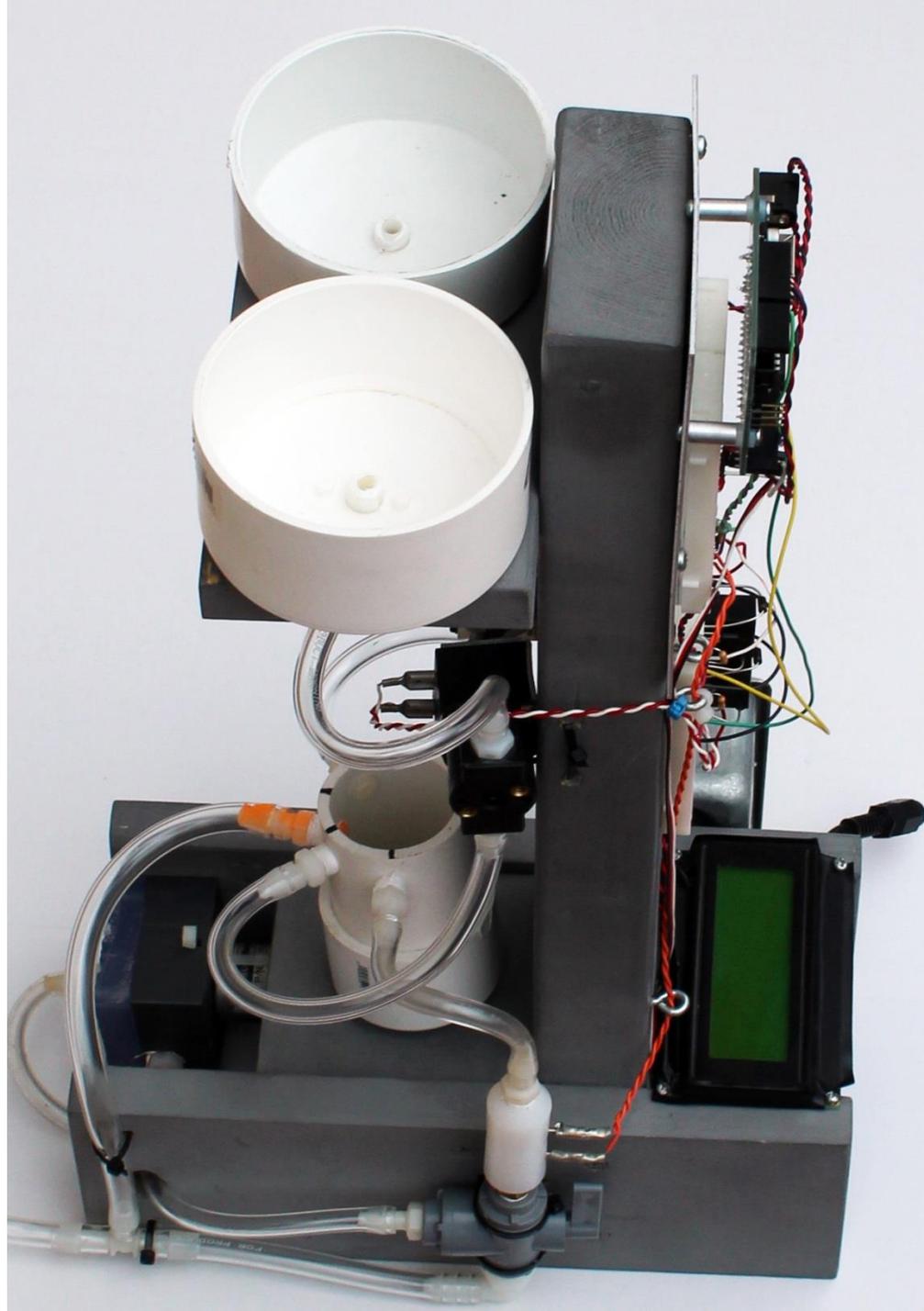
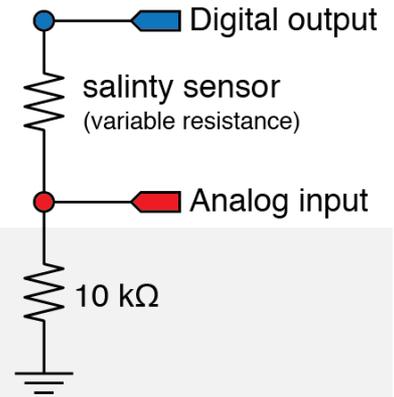


# Salinity Sensor Calibration Review



# Review of conductivity sensor wiring & programming



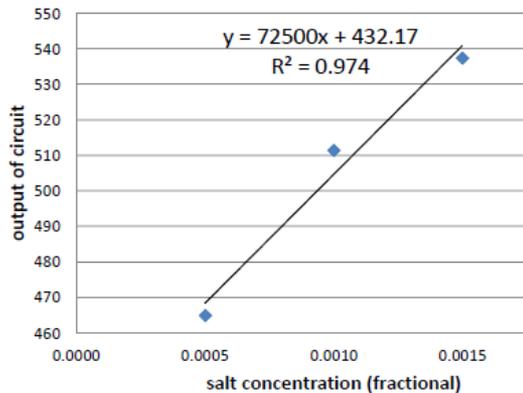
```
int salinity_power_pin = 4; // Digital I/O pin, Global variable
void setup()
{ Serial.begin(9600);
  pinMode (salinity_power_pin, OUTPUT);
}
void loop()
{ int salinity_input_pin = 2; // Analog input pin
  int nave=20; // Number of readings to average
  float salinity; // Float stores fractional reading from computed average

  salinity = sensor_reading_average (salinity_power_pin, salinity_input_pin, nave);
  Serial.println (salinity);
}
// -----
float sensor_reading_average (int power_pin, int input_pin, int n){
  int i;
  float reading;
  float sum; // Use floats for more precision and to prevent overflow
of sum
  sum = 0.0;
  for (i=1 ; i<=n ; i++){
    digitalWrite (power_pin, HIGH); // Turn on the sensor
    delay (100); // Wait to settle
    sum += analogRead (input_pin); // Add reading to the running sum
    digitalWrite (power_pin, LOW); // Turn off the sensor
    delay(10); // Wait between readings
  }
  reading = sum/float(n);
  return reading;
}
```

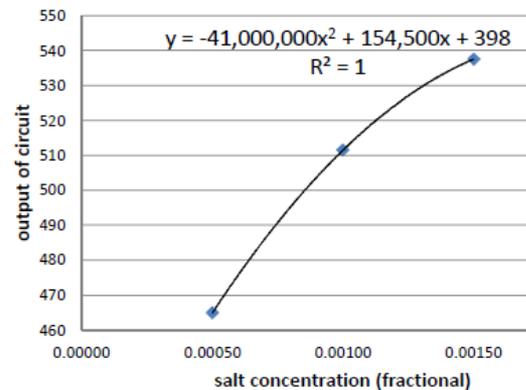
# Review of conductivity sensor calibration

- Collect analog output of salinity circuit, with output numbers ranging from 0 to 1023 (the Arduino has a 10-bit ADC)
- Perform linear regression to determine the expected output of the conductivity circuit as a function of salinity
- Which fit is the best?

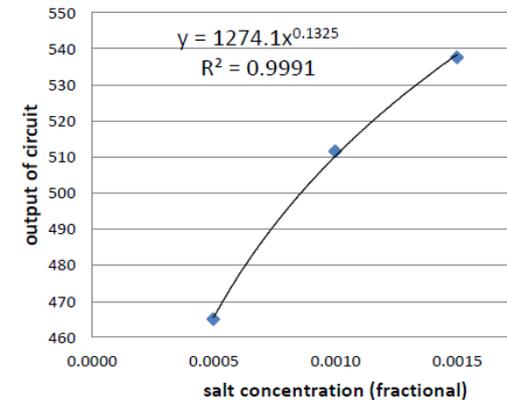
salt concentration (fractional)	Arduino output
0.0000	2.5
0.0005	465
0.0010	511.5
0.0015	537.5



**linear**



**polynomial**

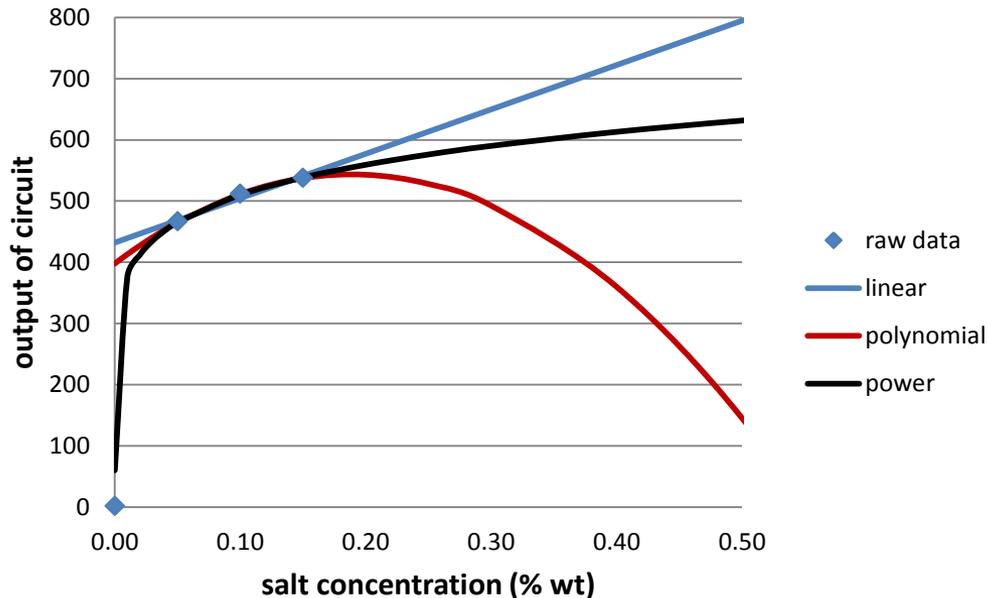


**power**

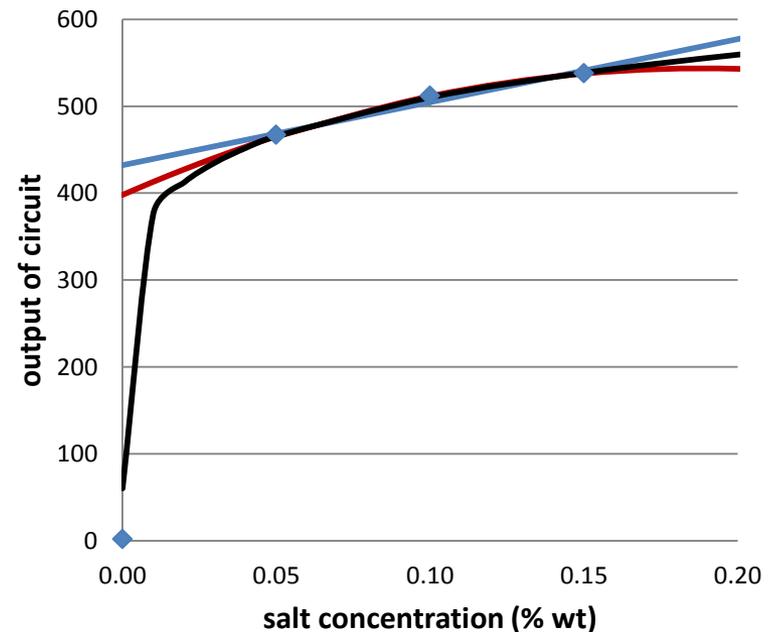
# Examine fits over possible salinity range

Consider how your fit behaves beyond 0.15 wt% salt since your salinity may increase well beyond 0.15% when salty water is added

## output vs salt concentration

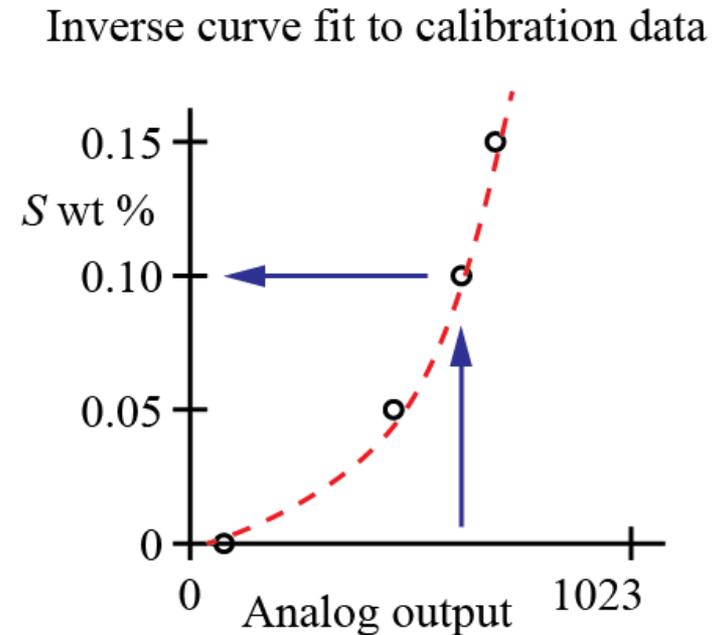
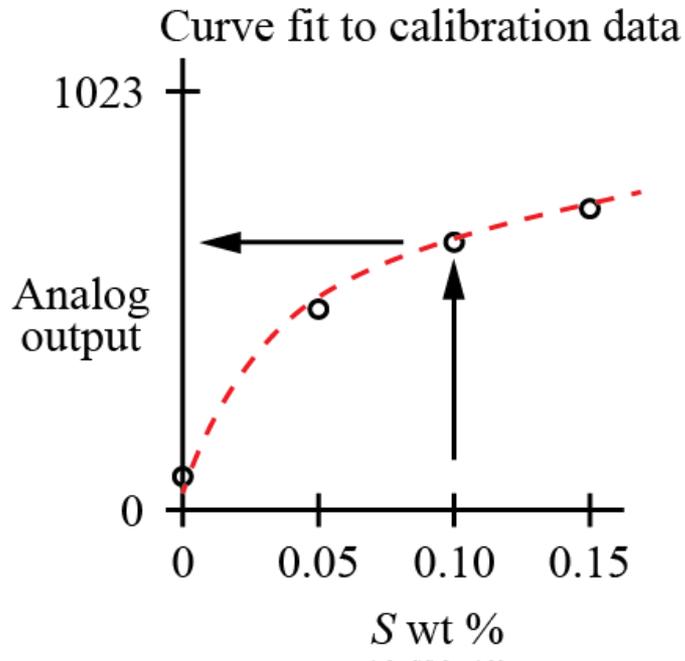


## output vs salt concentration



- Do you see any potential problems?
- Which fit seems to be the best? Why?

# Equations needed for salinity control sketch



Inverse equation can be obtained by

- Algebraic rearrangement of the calibration curve fit, or
- Performing another fit with x and y values swapped.

In either case, retain four or five digits in the curve fit coefficients